

UNIT-3

Stationary process:

A stochastic process $\{x(t), t \in T\}$ is a stationary process if finite dimensional distributions are invariant under arbitrary translation of the time parameter (i.e.,) if $\forall 'h'$,

$$P\{x(t_1) \leq x_1, x(t_2) \leq x_2 \dots x(t_n) \leq x_n\} =$$

$$P\{x(t_1+h) \leq x_1, x(t_2+h) \leq x_2 \dots x(t_n+h) \leq x_n\} \rightarrow (1)$$

for $t_i \in T, t_i+h \in T, h > 0$, then

$\{x(t), t \geq 0\}$ is a stationary process (or)

complete stationary (or) strict stationary; where

$x(t)$ represents the random component of time series.

$$y(t) = f(t) + x(t)$$

where $f(t)$ is the systematic part & it is

represented by a deterministic fn. of time. The

components of systematic part are trend,

cyclical & seasonal component. Model representing

random part are discussed for stationary

stochastic process.

The process is a stationary of order 'n' equ (1) holds for some particular 'n'. The stochastic process is a covariance stationary or ~~covariance~~ wide-sense stationary or weak-sense stationary if the covariance function

$$\text{cov}[X(t), X(t+h)] = E[X(t) \cdot X(t+h)] - E[X(t)] \cdot E[X(t+h)]$$

depends only on 'h' and $\forall t \in T$.

Ex: 1

Let $\{X(t), t \geq 0\}$ be the stochastic process with p.m.f.

$$P\{X(t) = n\} = \frac{e^{-\lambda t} (\lambda t)^n}{n!}; \lambda > 0, n = 0, 1, 2, \dots$$

Soln:

$$E[X(t)] = \lambda t$$

$$V[X(t)] = \lambda t$$

\Rightarrow Mean and variance depends on 't'.

Hence the process is not a stationary but it is evolutionary process.

Ex: 2

Let $\{x(t), t \geq 1\}$ be the stochastic process having mean 0 and var 1. Further $\{x_n\}$ be the seq of independent r.v's.

Soln:

$$E[x(t)] = 0$$

$$V[x(t)] = 1 \text{ is indept. of 't' ...}$$

$\Rightarrow x(t)$ is a stationary process.

$$\text{cov}[x(t), x(t+h)] = E[x(t) \cdot x(t+h)] - E[x(t)] \cdot E[x(t+h)].$$

$$= E[x(t) \cdot x(t+h)] - 0$$

$$= \begin{cases} V[x(t)] & \text{if } h=0. \\ 0 & \text{if } h \neq 0 \end{cases}$$

$$\text{cov}[x(t), x(t+h)] = \begin{cases} 1 & \text{if } h=0 \\ 0 & \text{if } h \neq 0. \end{cases}$$

$\Rightarrow \text{cov}[x(t), x(t+h)]$ is an indept. of 't'.

Hence $\{x(t), t \geq 1\}$ is a covariance stationary

(or) weak sense stationary.

Ex: 3

Let us consider the stochastic process

$\{x(t), t \geq 0\}$ where $x(t) = A_1 + A_2 t$; where

A_1, A_2 are indept. r.v.'s with

$$E(A_i) = \mu_i, \quad v(A_i) = \sigma_i^2, \quad \text{for } i = 1, 2.$$

Soln:

Given that,

$$x(t) = A_1 + A_2 t,$$

where A_1, A_2 are indept. r.v.'s with

$$E(A_1) = \mu_1,$$

$$E(A_2) = \mu_2$$

$$v(A_1) = \sigma_1^2$$

$$v(A_2) = \sigma_2^2$$

$$x(t) = A_1 + A_2 t$$

Taking expectation on both sides,

$$E[x(t)] = E[A_1 + A_2 t]$$

$$= E(A_1) + t E(A_2)$$

$$E[x(t)] = \mu_1 + t \mu_2 \rightarrow (1)$$

$$v[x(t)] = E[x(t)]^2 - \{E[x(t)]\}^2$$

$$\text{Consider } E[x(t)]^2 = E[A_1 + A_2 t]^2$$

$$v(x) = E(x^2) - [E(x)]^2$$

$$v(x) + [E(x)]^2 = E(x^2)$$

$$\sigma_1^2 + \mu_1^2 = E(x^2)$$

$$\begin{aligned}
 E[X(t)]^2 &= E[A_1 + A_2 t]^2 \\
 &= E[A_1^2 + A_2^2 t^2 + 2tA_1A_2] \\
 &= E[A_1^2] + t^2 E[A_2^2] + 2t E[A_1A_2] \\
 &= [\sigma_1^2 + \alpha_1^2] + t^2 [\sigma_2^2 + \alpha_2^2] + 2t \alpha_1 \alpha_2 \\
 &= [\sigma_1^2 + t^2 \sigma_2^2] + [\alpha_1^2 + t^2 \alpha_2^2] + 2t \alpha_1 \alpha_2
 \end{aligned}$$

$$V[X(t)] = E[X(t)]^2 - \{E[X(t)]\}^2$$

$$\begin{aligned}
 &= [\sigma_1^2 + t^2 \sigma_2^2 + (\alpha_1^2 + t^2 \alpha_2^2) + 2t \alpha_1 \alpha_2] - [\alpha_1 + \alpha_2 t]^2 \\
 &= [\sigma_1^2 + t^2 \sigma_2^2 + \alpha_1^2 + t^2 \alpha_2^2 + 2t \alpha_1 \alpha_2] - [\alpha_1^2 + 2\alpha_1 \alpha_2 t + \alpha_2^2 t^2] \\
 &= \sigma_1^2 + t^2 \sigma_2^2
 \end{aligned}$$

$$\therefore V[X(t)] = \sigma_1^2 + t^2 \sigma_2^2$$

Since mean and variance are the func. of t ,
the process is not stationary. Then the

covariance fn is-

$$\text{Cov}[X(t), X(s)] = E[X(t) \cdot X(s)] - E[X(t)] \cdot E[X(s)]$$

Then,

$$\begin{aligned}
 E[X(t) \cdot X(s)] &= E[(A_1 + A_2 t)(A_1 + A_2 s)] \\
 &= E[A_1^2 + A_1 A_2 s + A_1 A_2 t + A_2^2 t s] \\
 &= E[A_1^2] + s E[A_1 A_2] + t E[A_1 A_2] + t s E[A_2^2] \\
 &= (\sigma_1^2 + \alpha_1^2) + s(\alpha_1 \alpha_2) + t(\alpha_1 \alpha_2) + t s (\sigma_2^2 + \alpha_2^2)
 \end{aligned}$$

$$\begin{aligned}
\therefore \text{cov}[X(t) \cdot X(s)] &= \sigma_1^2 + \alpha_1^2 + s\alpha_1\alpha_2 + t\alpha_1\alpha_2 \\
&\quad + ts(\sigma_2^2 + \alpha_2^2) - \{(\alpha_1 + t\alpha_2)(\alpha_1 + s\alpha_2)\} \\
&= \sigma_1^2 + \alpha_1^2 + s\alpha_1\alpha_2 + t\alpha_1\alpha_2 + ts(\sigma_2^2 + \alpha_2^2) - \\
&\quad [\alpha_1^2 + \alpha_1\alpha_2s + \alpha_1\alpha_2t + ts\alpha_2^2] \\
&= \sigma_1^2 + \alpha_1^2 + s\alpha_1\alpha_2 + t\alpha_1\alpha_2 + ts\sigma_2^2 + ts\alpha_2^2 - \\
&\quad \alpha_1^2 - \alpha_1\alpha_2s - \alpha_1\alpha_2t - ts\alpha_2^2 \\
&= \sigma_1^2 + ts\sigma_2^2.
\end{aligned}$$

It depends on the time parameters t, s . Hence, the Covariance depends on t and s . The process is not covariance stationary but is an evolutionary process.

Ex: 4

Examine whether $\{X(t), t \geq 0\}$ is a stationary process or evolutionary process, where $X(t) = A \cos \omega t + B \sin \omega t$, where A and B are uncorrelated r.v.'s with mean 0 and var 1. ω is a +ve constant.

Soln:

Given that,

$$X(t) = A \cos \omega t + B \sin \omega t,$$

Further given that $\text{cov}(A, B) = 0$

$$E(A) = 0 = E(B) \quad ; \quad v(A) = v(B) = 1$$

$$\begin{aligned} \therefore E[X(t)] &= E[A \cos \omega t + B \sin \omega t] \\ &= E[A \cos \omega t] + E[B \sin \omega t] \\ &= \cos \omega t \cdot E(A) + \sin \omega t \cdot E(B). \end{aligned}$$

$$E[X(t)] = 0 + 0 = 0.$$

$$\begin{aligned} v[X(t)] &= E[A \cos \omega t + B \sin \omega t]^2 \\ &= E[A^2 \cos^2 \omega t + B^2 \sin^2 \omega t + 2AB \cos \omega t \sin \omega t] \\ &= \cos^2 \omega t E(A^2) + \sin^2 \omega t E(B^2) + 2 \cos \omega t \sin \omega t E(AB) \\ &= \cos^2 \omega t (1) + \sin^2 \omega t (1) + 2 \cos \omega t \sin \omega t \cdot 0 \\ &= \cos^2 \omega t + \sin^2 \omega t = 1. \end{aligned}$$

Stationary process, $X(t)$ is indepl. of t .

$$\text{Here, } E[X(t)] = 0 \quad ; \quad v[X(t)] = 1$$

$$\text{cov}[X(t), X(s)] = E[(A \cos \omega t + B \sin \omega t) (A \cos \omega s + B \sin \omega s)]$$

$$\begin{aligned} &= E[A^2 \cos \omega t \cos \omega s + AB \cos \omega t \sin \omega s \\ &\quad + B \sin \omega t A \cos \omega s + B^2 \sin \omega t \sin \omega s] \end{aligned}$$

$$\begin{aligned} &= E(A^2) \cos \omega t \cos \omega s + E(AB) \cos \omega t \cdot \sin \omega s \\ &\quad + E(AB) \cos \omega s \sin \omega t + E(B^2) \sin \omega t \sin \omega s. \end{aligned}$$

$$= \cos \omega t \cos \omega s + \sin \omega t \sin \omega s.$$

$$= \cos (s-t) \omega. \text{ -(formula),}$$

$$\Rightarrow \text{cov}[x(t), x(s)] = \cos (s-t) \omega,$$

depends on $(s-t)$. Hence $x(t)$ is not a
cov/- stationary,

Definition:

A stationary process $\{x(t), t \in T\}$ is said to be weakly stationary or stationary in wide-sense if the following are satisfied,

i) $E[x_t] = \mu < \infty$

ii) $E[x_t^2] < \infty$ exists.

iii) $\text{cov}(s, t) = \text{cov}(t-s)$.

Ex:

Let us consider the process $x(t)$ such that,

$$P\{x(t) = n\} = \frac{(at)^{n-1}}{(1+at)^{n+1}}, \quad \forall n = 1, 2, 3, \dots$$

Soln:

$$E(x) = \sum x p(x)$$

$$E[x(t)] = \sum_{n=1}^{\infty} [x=n] \cdot p[x(t) = n].$$

$$= \sum_{n=1}^{\infty} n \cdot \frac{(at)^{n-1}}{(1+at)^{n+1}}$$

$$\begin{aligned}
 E[x(t)] &= \sum_{n=1}^3 n \frac{(at)^{n-1}}{(1+at)^{n-1+2}} \\
 &= \frac{1}{(1+at)^2} \sum_{n=1}^3 n \frac{(at)^{n-1}}{(1+at)^{n-1}} \\
 &= \frac{1}{(1+at)^2} \left[1 + 2 \left(\frac{at}{1+at} \right) + 3 \left(\frac{at}{1+at} \right)^2 \right] \\
 &= \frac{1}{(1+at)^2} (1+at)^2 = 1
 \end{aligned}$$

$$\bar{u} \quad E[x(t)] = 1$$

$$V[x(t)] = E[x(t)]^2 - \{E[x(t)]\}^2$$

$$E[x(t)]^2 = \sum_{n=1}^3 n^2 \frac{(at)^{n-1}}{(1+at)^{n+1}}$$

$$= \sum_{n=1}^3 n(n-1) \frac{(at)^{n-1}}{(1+at)^{n+1}} + \sum_{n=1}^3 n \frac{at}{(1+at)^{n+1}}$$

$$= \frac{at}{(1+at)^3} \sum_{n=2}^3 \left[\frac{n(n-1)(at)^{n-2}}{(1+at)^{n-2}} \right] + \sum_{n=1}^3 n \frac{(at)^{n-1}}{(1+at)^{n+1}}$$

$$\left. \begin{aligned}
 \therefore n^2 &= n - n + n \\
 &= n(n-1) + n
 \end{aligned} \right\}$$

$$= \frac{at}{(1+at)^3} \left[\sum_{n=2}^3 \frac{n(n-1)(at)^{n-2}}{(1+at)^{n-2}} \right] + 1$$

$$= \frac{at}{(1+at)^3} \left[2 + (3 \times 2) \frac{at}{1+at} \right] + 1$$

$$E[x(t)]^2 = \frac{2at}{(1+at)^3} \left[1 + 3 \left(\frac{at}{1+at} \right) \right] + 1$$

$$= \frac{2at}{(1+at)^3} \cdot (1+at)^3 + 1$$

$$= 2at + 1$$

$$V[x(t)] = E[x(t)]^2 - \{E[x(t)]\}^2$$

$$= 2at + 1 - 1$$

$$= 2at, \text{ which depends on 't'}$$

Hence $x(t)$ is not stationary.

Ex:

$$\text{Let } x(t) = A_0 + A_1 t + A_2 t^2$$

where A_0, A_1, A_2 are uncorrelated with mean zero and variance 1. Find the mean and cov. fn. and state whether the process is stationary or not.

Solu

Given that

$$x(t) = A_0 + A_1 t + A_2 t^2$$

$$E(A_0) = E(A_1) = E(A_2) = 0$$

$$V(A_0) = V(A_1) = V(A_2) = 1$$

$$\text{cov}(A_i, A_j) = 0 ; \quad i = 0, 1, 2$$

$$j = 0, 1, 2 ; \quad i \neq j$$

then,

$$\begin{aligned} E[x(t)] &= E[A_0 + A_1 t + A_2 t^2] \\ &= E(A_0) + t E(A_1) + t^2 E(A_2) \\ &= 0 \end{aligned}$$

$$\begin{aligned} V[x(t)] &= E[x(t)]^2 - \{E[x(t)]\}^2 \\ &= E[x(t)]^2 - 0 \end{aligned}$$

$$\begin{aligned} E[x(t)]^2 &= E[A_0 + A_1 t + A_2 t^2]^2 \\ &= E(A_0)^2 + t^2 E(A_1^2) + t^4 E(A_2^2) \end{aligned}$$

$$E[x(t)]^2 = 1 + t^2 + t^4$$

$$\therefore V[x(t)] = 1 + t^2 + t^4$$

$$\begin{aligned} V(x) &= E(x^2) - [E(x)]^2 \\ E(x^2) &= V(x) + [E(x)]^2 \\ &= 1 + 0 \\ &= 1 \end{aligned}$$

$$\text{cov}[x(t), x(s)] = E[(A_0 + A_1 t + A_2 t^2)(A_0 + A_1 s + A_2 s^2)] - 0$$

$$\therefore \text{cov}(x, y) = E(x, y) - E(x)E(y)$$

$$= E[A_0^2 + A_0 A_1 s + A_0 A_2 s^2 + A_0 A_1 t + A_1^2 t s + A_1 A_2 t s^2 + A_0 A_2 t^2 + A_1 A_2 t^2 s + A_2^2 t^2 s^2]$$

$$= E(A_0^2) + s E(A_0 A_1) + s^2 E(A_0 A_2) + t E(A_1 A_1) + t s E(A_1^2) + t s^2 E(A_1 A_2) + t^2 E(A_0 A_2) + t^2 s E(A_1 A_2) + t^2 s^2 E(A_2^2)$$

$$= 1 + t s + t^2 s^2$$

Since $V[x(t)]$ and $\text{cov}[x(t), x(s)]$ are the fn of 't' the process $x(t)$ is not stationary. It is also not cov. stationary.

Models for the Generation of Random Part of Time Series:

(i) Purely Random process (white noise process)

Let $Y(t) = \phi(t) + x(t)$ be the time series, where $\phi(t)$ represents systematic part which includes trend, seasonal and cyclical components.

$x(t)$ represents the random part of the time series. A completely random process $\{x(t), t \in T\}$ has mean

$$E[x(t)] = \mu$$

$$V[x(t)] = \sigma^2$$

is the cov. fn. $C_k = E[x(t) \cdot x(t+k)] = 0 \quad \forall k \neq 0$

$$C_k = 0$$

\Rightarrow The process $x(t)$ is a cov. stationary process. μ & σ^2 are inde. of 't'. Then the process is said to be covariance stationary.

(ii) Auto Regressive process - Definition:

First order Markov process (or) Auto-Regressive process of order 1 [AR(1)]:

The process $\{x(t), t \in T\}$ has the structure $x(t) = a x(t-1) + \varepsilon_t, t = 1, 2, \dots$ — (1)

where ε_t is purely random process such that $E(\varepsilon_t) = 0; V(\varepsilon_t) = \sigma_\varepsilon^2 = \sigma^2$

(1) becomes,

$$x(t) - a x(t-1) = \varepsilon_t \quad \text{--- (2)}$$

Multiply (2) by $x(t-h)$,

$$x(t) x(t-h) - a x(t-1) x(t-h) = \varepsilon_t x(t-h)$$

Taking expectations on both sides, we get

$$E[x(t) \cdot x(t-h)] - a E[x(t-1) x(t-h)] = E[\varepsilon_t x(t-h)]$$

which is called as Yule-walker equations.

for $h=0$,

$$E[x(t) x(t-0)] - a E[x(t-1) x(t-0)] = E[\varepsilon_t x(t-0)]$$

$$\sigma_x^2 - a \rho(1) \sigma_x^2 = \sigma^2$$

$$\sigma_x^2 [1 - a \rho(1)] = \sigma^2$$

$$\sigma_x^2 = \frac{\sigma^2}{1 - a \rho(1)} \quad \text{--- (3)}$$

for $h=1$,

$$E[x(t) x(t-1)] - a E[x(t-1) x(t-1)] = E[\varepsilon_t x(t-1)]$$

$$\rho(1) \sigma_x^2 - a \rho(0) \sigma_x^2 = 0$$

$$\sigma_x^2 [\rho(1) - a \rho(0)] = 0$$

$$\rho(1) - a \rho(0) = 0$$

$$\rho(1) = a \rho(0)$$

$$\rho(1) = a \left\{ \because \rho(0) = 1 \right.$$

Substitute $\rho(1)$ in (3)

$$\sigma_x^2 = \frac{\sigma^2}{1 - a^2}$$

for $h=2$,

$$E[x(t) \cdot x(t-2)] - a E[x(t-1) x(t-2)] = E[\varepsilon_t x(t-2)]$$

$$P(2) \sigma_x^2 - a P(1) \sigma_x^2 = 0$$

$$\sigma_x^2 [P(2) - a P(1)] = 0$$

$$[P(2) - a P(1)] = 0$$

$$P(2) = a P(1)$$

$$P(2) = a \cdot a = a^2$$

⋮

for $h=n$, we get

$$P(n) = a^n$$

$\Rightarrow x(t)$ is covariance stationary.

Moving Average Process:

g^m [The process $\{x(t), t \in T\}$ is represented as

$$x(t) = a_0 \varepsilon_t + a_1 \varepsilon_{t-1} + \dots + a_k \varepsilon_{t-k} \quad \text{--- (1)}$$

where a_i 's are real constants and $\{\varepsilon_t\}$ is a purely random process such

that $E(\varepsilon_t) = 0$ & $V(\varepsilon_t) = \sigma^2$.

$x(t)$ can also be represented as

$$x(t) = \phi(B) \cdot \varepsilon_t$$

where $\phi(B) = \sum_{r=0}^h a_r B^r$

B = Backshift operator

i.e. $B[x(t)] = x(t-1)$

$B^2[x(t)] = x(t-2), \dots$

when $a_h \neq 0$, $\{x(t), t \in T\}$ is called as moving average process of order ' h '.

$$E[x(t)] = E[\phi(B)\epsilon_t]$$

$$= \phi(B) E(\epsilon_t) = 0$$

The cov. fn. $C_k = E[x(t) \cdot x(t-k)]$

$$C_k = E \left[\left[a_0 \epsilon_t + a_1 \epsilon_{t-1} + \dots + a_k \epsilon_{t-k} + a_{k+1} \epsilon_{t-k-1} + \dots + a_h \epsilon_{t-h} \right] \cdot \left[a_0 \epsilon_{t-k} + a_1 \epsilon_{t-k-1} + \dots + a_{h-k} \epsilon_{t-k-h} + \dots + a_h \epsilon_{t-k-h} \right] \right]$$

$$C_k = E \left[a_0 a_k \epsilon_{t-k}^2 + a_1 a_{k+1} \epsilon_{t-k-1}^2 + \dots + a_{h-k} a_h \epsilon_{t-h}^2 + \sum_{r \neq t} a_r a_t \epsilon_r \epsilon_t \right]$$

$$= a_0 a_k E(\epsilon_{t-k}^2) + a_1 a_{k+1} E(\epsilon_{t-k-1}^2) + \dots + a_{h-k} a_h E(\epsilon_{t-h}^2)$$

$$\Rightarrow C_k = \begin{cases} (a_0 a_k + a_1 a_{k+1} + \dots + a_{h-k} a_h) \sigma^2 & ; k \leq h \\ 0 & ; k > h \end{cases}$$

The necessary condition for representing the stochastic process by moving average of order ' h ' is that $C_k = 0$ for $k > h$

$$\therefore \rho_k = \frac{c_k}{c_0} = \begin{cases} \frac{a_0 a_k + a_1 a_{k-1} + \dots + a_{h-k} a_h}{a_0^2 + a_1^2 + \dots + a_h^2} ; k \leq h \\ 0 ; k > h \end{cases}$$

$\Rightarrow x(t)$ is a cov. stationary.

Note:

$$\forall a_k = \frac{1}{h+1}, \forall k = 0, 1, \dots, h$$

$$\text{then } \rho = \frac{h-k+1}{h+1} = \frac{h+1-k}{h+1}$$

$$\rho = \begin{cases} 1 - \frac{k}{h+1} ; 0 \leq k \leq h \\ 0 ; \text{o.w} \end{cases}$$

The graph of the corr. fn. is called as correlogram.

Auto-Regressive Process of order 2 [AR(2)]:

The process $x(t)$ is said to be second order Auto-Regressive if it satisfies the difference eqn,

$$x(t) + a_1 x(t-1) + a_2 x(t-2) = \varepsilon_t \quad \forall t \geq 0 \quad \text{--- (1)}$$

where a_1 & a_2 are constants, ε_t is a purely random process

By using backward shifting operator ' B ', eqn (1) can be written as

$$B^0 x(t) + a_1 B^1 x(t) + a_2 B^2 x(t) = \varepsilon_t$$

$$\left[1 + a_1 B + a_2 B^2 \right] x(t) = \varepsilon_t$$

Assume that μ_1 & μ_2 are the distinct roots of the characteristic eqn. of the form

$$\phi(z) = z^2 + a_1 z + a_2 = 0 \quad \text{--- (2)}$$

neglecting for large t , we get

$$(1 - \mu_1 B)(1 - \mu_2 B) x(t) = \varepsilon_t \quad \text{--- (3)}$$

$$x(t) = \frac{\varepsilon_t}{(1 - \mu_1 B)(1 - \mu_2 B)}$$

$$= \left[(1 - \mu_1 B)(1 - \mu_2 B) \right]^{-1} \varepsilon_t$$

x is \div by $(\mu_1 - \mu_2)$ on RHS,

$$x(t) = \frac{1}{\mu_1 - \mu_2} \left[\frac{\mu_1 - \mu_2}{(1 - \mu_1 B)(1 - \mu_2 B)} \right] \varepsilon_t$$

$$= \frac{1}{\mu_1 - \mu_2} \left[\frac{\mu_1 (1 - \mu_2 B) - \mu_2 (1 - \mu_1 B)}{(1 - \mu_1 B)(1 - \mu_2 B)} \right] \varepsilon_t$$

$$= \frac{1}{\mu_1 - \mu_2} \left[\frac{\mu_1}{1 - \mu_1 B} - \frac{\mu_2}{1 - \mu_2 B} \right] \varepsilon_t$$

$\left\{ \begin{array}{l} \because \mu_1 - \mu_1 \mu_2 B - \mu_2 + \mu_1 \mu_2 B = \mu_1 - \mu_2 \end{array} \right.$

on expanding, we get -

$$x(t) = \frac{1}{\mu_1 - \mu_2} \sum_{s=0}^{\infty} (\mu_1^{s+1} - \mu_2^{s+1}) \varepsilon_{t-s} \quad \text{--- (4)}$$

Let us consider the eqn (1)

$$x(t) + a_1 x(t-1) + a_2 x(t-2) = \varepsilon_t$$

Multiply eqn (1) by $x(t-h)$ and taking expectation on both sides we get

$$E[x(t) \cdot x(t-h)] + a_1 E[x(t-1) \cdot x(t-h)] + a_2 E[x(t-2) \cdot x(t-h)] = E[\varepsilon_t x(t-h)]$$

which is called as Yule-Walker equation
for $h=0$,

$$E[x(t) \cdot x(t)] + a_1 E[x(t-1) \cdot x(t)] + a_2 E[x(t-2) \cdot x(t)] = E[\varepsilon_t x(t)]$$

$$\sigma_x^2 + a_1 \rho(1) \sigma_x^2 + a_2 \rho(2) \sigma_x^2 = \sigma^2$$

$$\sigma_x^2 [1 + a_1 \rho(1) + a_2 \rho(2)] = \sigma^2$$

$$\Rightarrow \sigma_x^2 = \frac{\sigma^2}{(1 + a_1 \rho(1) + a_2 \rho(2))} \quad (5)$$

for $h=1$,

$$E[x(t) \cdot x(t-1)] + a_1 E[x(t-1) \cdot x(t-1)] + a_2 E[x(t-2) \cdot x(t-1)] = E[\varepsilon_t x(t-1)]$$

$$\rho(1) \sigma_x^2 + a_1 \rho(0) \sigma_x^2 + a_2 \rho(1) \sigma_x^2 = 0$$

$$\sigma_x^2 [\rho(1) + a_1 \rho(0) + a_2 \rho(1)] = 0$$

$$\rho(1) + a_1 \rho(0) + a_2 \rho(1) = 0$$

$$P(1) + a_1 + a_2 P(1) = 0 \quad \left\{ \because P(0) = 1 \right\}$$

$$P(1)[1 + a_2] + a_1 = 0.$$

$$P(1)[1 + a_2] = -a_1,$$

$$P(1) = \frac{-a_1}{1 + a_2}$$

for $h = 2$,

$$E[x(t)x(t-2)] + a_1 E[x(t-1)x(t-2)] + a_2 E[x(t-2)x(t-2)] \\ = E[\varepsilon_t x(t-2)]$$

$$P(2)\sigma_x^2 + a_1 P(1)\sigma_x^2 + a_2 P(0)\sigma_x^2 = 0.$$

$$\sigma_x^2 [P(2) + a_1 P(1) + a_2 P(0)] = 0.$$

$$P(2) + a_1 P(1) + a_2 = 0.$$

$$P(2) + a_1 \left(\frac{-a_1}{1 + a_2} \right) + a_2 = 0.$$

$$P(2) - \frac{a_1^2}{1 + a_2} + a_2 = 0$$

$$P(2) = \frac{a_1^2}{1 + a_2} - a_2$$

Substitute $P(1)$ & $P(2)$ in eqn (5)

$$\sigma_x^2 = \frac{\sigma_x^2}{1 + a_1 \left(\frac{-a_1}{1 + a_2} \right) + a_2 \left(\frac{a_1^2}{1 + a_2} - a_2 \right)}$$

Let us consider the denominator,

$$\begin{aligned}
& 1 - \frac{a_1^2}{1+a_2} + \frac{a_1^2 a_2}{1+a_2} - a_2^2 \\
&= \frac{(1+a_2) - a_1^2 + a_1^2 a_2 - a_2^2 (1+a_2)}{1+a_2} \\
&= \frac{(1+a_2) - a_1^2 + a_1^2 a_2 - a_2^2 + a_2^3}{1+a_2} \\
&= \frac{(1+a_2)(1-a_2^2) - a_1^2(1-a_2)}{1+a_2} \\
&= \frac{(1+a_2)(1+a_2)(1-a_2) - a_1^2(1-a_2)}{1+a_2} \\
&= \frac{(1-a_2) \left[(1+a_2)(1+a_2) - a_1^2 \right]}{1+a_2} \\
&= \frac{(1-a_2) \left[(1+a_2)^2 - a_1^2 \right]}{1+a_2} \\
&= \frac{(1-a_2) \left[(1+a_2) + a_1 \right] \left[(1+a_2) - a_1 \right]}{1+a_2} \\
&= \frac{(1-a_2) (1+a_1+a_2) (1-a_1+a_2)}{1+a_2} \\
\therefore \sigma_n^2 &= \frac{\sigma^2 (1+a_2)}{(1-a_2) (1+a_1+a_2) (1-a_1+a_2)}
\end{aligned}$$

In general, the Yule-Walker eqns. are

$$\rho(k) + a_1 \rho(k-1) + a_2 \rho(k-2) = 0 \text{ for } k=1, 2, 3, \dots$$

Solving this difference eqn for $\rho(k)$, we get

$$\rho(k) = \alpha_1 \mu_1^k + \alpha_2 \mu_2^k$$

where α_1 & α_2 are constants and they are determined by using $\rho(0) = 1$ & $\rho(1) = \frac{-a_1}{1+a_2}$

thus for unequal roots i.e. ($\mu_1 \neq \mu_2$)

$$\rho(k) = \frac{(1-\mu_2^2)\mu_1^{k+1} - (1-\mu_1^2)\mu_2^{k+1}}{(\mu_1 - \mu_2)(1 + \mu_1\mu_2)}; k=0, 1, \dots$$

Note:

when the roots are real and equal ($\mu = \mu_1 = \mu_2$) then $\rho(k)$ can be written as,

$$\rho(k) = \left[1 + \frac{k(1-\mu^2)}{(1+\mu^2)} \right] \mu^k; k=0, 1, \dots$$

\Rightarrow The process is cov. stationary and the graph of the $\rho(k)$ is called as correlogram and it is oscillatory.

Auto-regressive process of order k : AR(k)

The process $x(t)$ is said to be an Auto-regressive process of order ' k ', if it satisfies the difference eqn

$$x(t) + a_1 x(t-1) + a_2 x(t-2) + \dots + a_k x(t-k) = \varepsilon_t$$

————— (1)

where a_1, a_2, \dots, a_k are all constants
 $\Rightarrow a_k \neq 0$ and ε_t is purely random

process $\Rightarrow E(\varepsilon_t) = 0; V(\varepsilon_t) = \sigma^2$

eqn (1) can be rewritten as,

$$x(t) + a_1 B x(t) + a_2 B^2 x(t) + \dots + a_k B^k x(t) = \varepsilon_t$$

$$\left[1 + a_1 B + a_2 B^2 + \dots + a_k B^k \right] x(t) = \varepsilon_t$$

$$\alpha(B) x(t) = \varepsilon_t \quad \text{--- (2)}$$

where $\alpha(B) = \sum_{r=0}^k a_r B^r$; $a_0 = 1$ &

B is a backward shift operator.

The solu. of the eqn (2) can be written as

$$x(t) = \phi(t) + \alpha(B)^{-1} \varepsilon_t \quad \text{--- (3)}$$

$\phi(t) = A_1 M_1^t + A_2 M_2^t + \dots + A_k M_k^t$ and

M_1, M_2, \dots, M_k are all distinct roots of the polynomial

$$g(z) = z^k + a_1 z^{k-1} + \dots + a_k$$

for the asymptotic stationarity of $x(t)$, all M_k 's must be less than 1 in absolute value.

Expanding the series $\alpha(B)^{-1} = \prod_{i=1}^k (1 - M_i B)^{-1}$ into partial fraction, the particular solu.

obtained as

$$x(t) = \sum_{r=0}^{\infty} b_r \varepsilon_{t-r}$$

where b_r are constants involving μ_i 's

thus an auto-regressive process can be represented by an Moving Average process of infinite order.

Properties of covariance function & correlation function:

(i) cov. fn. is even & +ve definite.

(ii) Correlation fn. has the representation as

$$\rho(k) = \int_{-\pi}^{\pi} e^{ik\omega} dF(\omega)$$

where $F(\omega)$ is the dist. fn. and it determines a characteristic fn. uniquely.

when $F(\omega)$ is absolutely continuous

then

$$\phi(\omega) = \frac{dF(\omega)}{d\omega}$$

$$= \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \rho(k) e^{-ik\omega}$$

IIIly, the cov. fn. c_k can be represented

as,

$$c_k = \int_{-\pi}^{\pi} e^{ik\omega} dF(\omega)$$

where $dF(\omega) = c_0 dF_1(\omega)$, where

$$dF(\omega) = \phi(\omega) d\omega \quad \text{and}$$

$$\phi(\omega) = \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} C_k e^{-ik\omega}$$

\Rightarrow The fn. $F_1(\omega)$ & $F(\omega)$ are called integrated spectrum.

The fn $\phi(\omega)$ is called spectral density fn. and $\phi_1(\omega)$ is normalized spectral density fn. of the process.

Eg:

Let $x(t)$ be a purely random process with $E[x(t)] = 0$

$$E(x_r \cdot x_s) = \begin{cases} \sigma^2 & ; r = s \\ 0 & ; r \neq s \end{cases}$$

$$\Rightarrow C_k = 0 \quad \text{for } k \neq 0, \quad C_0 = \sigma^2$$

$$\therefore \phi(\omega) = \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} C_k e^{-ik\omega}$$

$$= \frac{\sigma^2}{2\pi} ; \quad -\pi \leq \omega \leq \pi$$

thus the fn. C_k may be obtained from the relation

$$C_k = \int_{-\pi}^{\pi} e^{ik\omega} dF(\omega)$$

Spectral density of time series: (continuous parameter processes)

when the time parameters are continuous, the s.p. $\{x(t), -\infty < t < \infty\}$ is wide-sense stationary iff $\mu = m$

$E[x(t)] = m$ (say) is indep. of t
cov. fn. $R(v) = E\{[x(t) - m][x(t+v) - m]\}$ is a fn. of v

The cov. fn. $R(v)$ can be represented as

$$R(v) = \int_{-\infty}^{\infty} e^{i v \omega} dF(\omega)$$

where F is a dist. fn. & $dF(\omega) = f(\omega)d\omega$

The spectral density of the process is obtained as

$$f(\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-i v \omega} R(v) dv$$

which is due to Bochner's inversion theorem.

Example:

find the spectral density of the process $x(t)$ with cov. fn.

$$R(v) = a e^{-b|v|}$$

Soln.

Given that the cov. fn.

$$R(v) = a e^{-b|v|}$$

Then by using Bochner's inversion then the spectral density is obtained as

$$\begin{aligned}
 \phi(\omega) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-i\nu\omega} R(\nu) d\nu \\
 &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-i\nu\omega} a \cdot e^{-b|\nu|} d\nu \\
 &= \frac{a}{2\pi} \left[\int_{-\infty}^0 e^{-i\nu\omega} e^{-b(-\nu)} d\nu + \int_0^{\infty} e^{-i\nu\omega} e^{-b(\nu)} d\nu \right] \\
 &= \frac{a}{2\pi} \left[\int_{-\infty}^0 e^{(b-i\omega)\nu} d\nu + \int_0^{\infty} e^{-(b+i\omega)\nu} d\nu \right] \\
 &= \frac{a}{2\pi} \left[\frac{e^{(b-i\omega)\nu}}{(b-i\omega)} \Big|_{-\infty}^0 + \frac{e^{-(b+i\omega)\nu}}{-(b+i\omega)} \Big|_0^{\infty} \right] \\
 &= \frac{a}{2\pi} \left[\frac{1}{b-i\omega} + \frac{1}{b+i\omega} \right] \\
 &= \frac{a}{2\pi} \left[\frac{b+i\omega + b-i\omega}{(b-i\omega)(b+i\omega)} \right] \\
 &= \frac{2ab}{2\pi} \left[\frac{1}{b^2 + \omega^2} \right] \quad \left\{ \begin{array}{l} \because b^2 - i\omega b + i\omega b - (i\omega)^2 \\ i^2 = -1 \end{array} \right. \\
 \therefore \phi(\omega) &= \frac{ab}{\pi} \left[\frac{1}{b^2 + \omega^2} \right]
 \end{aligned}$$

Example

Find the spectral density of the process when $R(v) = e^{-v^2/2}$

Soln

Given that the cov. fun as $R(v) = e^{-v^2/2}$

By using Bochner's inversion thm, the spectral density is obtained as

$$\begin{aligned}\phi(\omega) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-i v \omega} R(v) dv \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-i v \omega} e^{-v^2/2} dv \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-\frac{1}{2}(v^2 + 2i v \omega)} dv\end{aligned}$$

Add & subtract $(i\omega)^2$

$$\begin{aligned}\phi(\omega) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-\frac{1}{2}[v^2 + 2i v \omega + (i\omega)^2 - (i\omega)^2]} dv \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-\frac{1}{2}(v+i\omega)^2} e^{-\frac{1}{2}\omega^2} dv\end{aligned}$$

$$= \frac{1}{2\pi} e^{-\frac{1}{2}\omega^2} \int_{-\infty}^{\infty} e^{-\frac{1}{2}(v+i\omega)^2} dv$$

$$= \frac{1}{2\pi} e^{-\frac{1}{2}\omega^2} \sqrt{2\pi} \left\{ \because \int_{-\infty}^{\infty} e^{-\frac{1}{2}(v+i\omega)^2} dv = \sqrt{2\pi} \right.$$

$$\phi(\omega) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}\omega^2}$$